

Contents lists available at ScienceDirect

Journal of Functional Analysis

journal homepage: www.elsevier.com/locate/jfa

Full Length Article

Piecewise-analytic interfaces with weakly singular points of arbitrary order always scatter



Functiona Analysi

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ARTICLE INFO

Article history: Received 10 December 2021 Accepted 25 November 2022 Available online 7 December 2022 Communicated by Guido De Philippis

Keywords: Inverse medium scattering Inverse source problem Weakly singular points Uniqueness

ABSTRACT

It is proved that an inhomogeneous medium whose boundary contains a weakly singular point of arbitrary order scatters every incoming wave. Similarly, a compactly supported source term with weakly singular points on the boundary always radiates acoustic waves. These results imply the absence of non-scattering energies and non-radiating sources in a domain whose boundary is piecewise analytic but not infinitely smooth. Local uniqueness results with a single far-field pattern are obtained for inverse source and inverse medium scattering problems. Our arguments provide a rather weak condition on scattering interfaces and refractive index functions to guarantee the scattering phenomena that the scattered fields cannot vanish identically.

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1. Introduction and main results

Let $D \subset \mathbb{R}^2$ be a bounded (open) domain such that its exterior $D^e := \mathbb{R}^2 \setminus \overline{D}$ is connected. In this paper, the closure of D represents either the support of an acoustic source $s \in L^{\infty}(\mathbb{R}^2)$ or the support of the contrast function 1-q of an inhomogeneous medium. The source term s is called non-radiating if it does not radiate wave fields at infinity, that is, the far-field pattern caused by s vanishes identically. Analogously, if a penetrable obstacle D scatters some incoming wave trivially at the wavenumber $\kappa > 0$, then κ is called a non-scattering energy. The study of non-scattering energies dates back to [26] in the case of a convex (planar) corner domain, where the notion of scattering support for an inhomogeneous medium was explored. The existence of nonradiating sources and non-scattering energies may cause essential difficulties in detecting a target from far-field measurements. It is well known that non-scattering energies and non-radiating sources can be excluded if ∂D contains a curvilinear polygonal/polyhedral corner or a circular conic corner, in other words, corners always scatter; see e.g., [4,14,15, 20,26,32] and recent publications [5,6,8,9,35]. The aforementioned "visible" corners can be interpreted as strongly singular points, since the first derivative of the function for parameterizing ∂D is usually discontinuous at these points. In this paper, the boundary ∂D is supposed to be C^1 -smooth and piecewise analytic with a finite number of weakly singular points.

Throughout the paper we set $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$ and $B_{\epsilon}(x) := \{y = (y_1, y_2) \in \mathbb{R}^2 : |y - x| < \epsilon\}$. Write $B_{\epsilon} = B_{\epsilon}(O)$ where O = (0, 0) always denotes the origin. Set $\partial_j := \partial/\partial x_j$ for j = 1, 2. Below we state the definition of a weakly singular point.

Definition 1.1. The point $O \in \partial D$ is called a weakly singular point of order $m \geq 2$ $(m \in \mathbb{N})$ if the subboundary $B_{\epsilon}(O) \cap \partial D$ for some $\epsilon > 0$, after a necessary coordinate translation and rotation, can be parameterized by the piecewise polynomial $x_2 = f(x_1), x_1 \in (-\epsilon/2, \epsilon/2)$, where

$$f(x_1) = \begin{cases} \sum_{l \in \mathbb{N}_0} \frac{f_l^+}{l!} x_1^l, & -\epsilon/2 < x_1 \le 0, \\ \sum_{l \in \mathbb{N}_0} \frac{f_l^-}{l!} x_1^l, & 0 \le x_1 < \epsilon/2. \end{cases}$$
(1.1)

Here, the real-valued coefficients $\{f_l^{\pm}\}_{l=1}^{\infty}$ satisfy the relations

$$f_l^+ = f_l^- := f_l, \quad \forall \ 0 \le l < m \quad \text{and} \qquad f_m^+ \ne f_m^-,$$

with $f_l = 0$ for l = 0, 1. Moreover, the series (1.1) in $x_1 \ge 0$ (resp. $x_1 \le 0$) converges at $x_1 = 0$.

A weakly singular point defined by Definition 1.1 can be regarded as the intersection of two analytic curves. We require $m \ge 2$ in the above definition, because a singular point of order one is exactly strongly singular in the sense that f is continuous and the first derivative $f' := df/dx_1$ is discontinuous at O. Obviously, each planar corner point of a polygon is strongly singular. If O is weakly singular, then ∂D is piecewise analytic but cannot be C^{∞} -smooth at this point. The purpose of this paper is to prove that

- (i) An inhomogeneous medium with a weakly singular point of arbitrary order lying on the support \overline{D} of the contrast function scatters every incoming wave (Theorem 1.4).
- (ii) A source term embedded in an inhomogeneous medium with a weakly singular point of arbitrary order lying on the support \overline{D} of the source function always radiates acoustic waves non-trivially (Theorem 1.2).
- (iii) Local uniqueness results in recovering source terms and the shape of an inhomogeneous medium (Theorems 1.3 and 1.5).

The first/second assertion implies the absence of non-scattering energies/non-radiating sources, when the piecewise analytic boundary ∂D contains at least one weakly singular point of arbitrary order. We state our main results for inverse medium scattering and inverse source problems separately as follows.

1.1. Radiating sources in an inhomogeneous medium

Consider the wave propagation caused by a time-harmonic acoustic source embedded in an inhomogeneous background medium in two dimensions. This can be modeled by the inhomogeneous Helmholtz equation

$$\Delta v(x) + \kappa^2 \mathfrak{n}(x) v(x) = s(x) \quad \text{in} \quad \mathbb{R}^2.$$
(1.2)

In this paper, the potential (or refractive index) function \mathfrak{n} of the inhomogeneous background medium is supposed to be real-analytic in B_R and $\mathfrak{n}(x) \equiv 1$ in |x| > R for some R > 0. The number $\kappa > 0$ represents the wavenumber of the homogeneous medium in |x| > R and $s \in L^2(\mathbb{R}^2)$ is a source term compactly supported in $D \subset B_R$. Further, it is supposed that $s = S|_{\overline{D}}$ where S is a real-analytic function defined in a neighborhood of D. Since v is outgoing at infinity, it is required to satisfy the Sommerfeld radiation condition

$$\lim_{|x|\to\infty}\sqrt{r}\left\{\frac{\partial v}{\partial r} - i\kappa v\right\} = 0, \quad r = |x|, \tag{1.3}$$

uniformly in all directions $\hat{x} := x/|x| \in \mathbb{S} := \{x \in \mathbb{R}^2 : |x| = 1\}$. In particular, the Sommerfeld radiation condition (1.3) leads to the asymptotic expansion

$$v(x) = \frac{e^{i\kappa r}}{\sqrt{r}} v^{\infty}(\hat{x}) + \mathcal{O}\left(\frac{1}{r^{3/2}}\right), \quad r \to +\infty.$$

The function $v^{\infty}(\hat{x})$ is an analytic function defined on S and is usually referred to as the *far-field pattern* or the *scattering amplitude*. The vector $\hat{x} \in S$ is called the observation

direction of the far-field pattern. Using the variational approach, one can readily prove that the system (1.2)-(1.3) admits a unique solution in $H^2_{loc}(\mathbb{R}^2)$; see [12, Chapter 5] or [7, Chapter 5]. Since the far-field pattern encodes information on the source, we are interested in the inverse problem of recovering the source support ∂D and/or the source term s(x) from the far-field pattern over all observation directions at a fixed frequency.

The source term s(x) is called *non-radiating* if v^{∞} vanishes identically. For example, setting $s := (\Delta + \kappa^2 \mathfrak{n}(x))\varphi$ for some $\varphi \in C_0^{\infty}(B_R)$, it is easy to observe that the unique radiating solution to (1.2) is exactly φ , which has the vanishing far-field pattern. Hence, in general a single far-field pattern cannot uniquely determine a source function (even its support), due to the existence of non-radiating sources. In the following two theorems, we shall characterize a class of radiating sources and extract partial or entire information of an analytical source term at a weakly singular point.

Theorem 1.2 (Characterization of radiating sources). If $O \in \partial D$ is a weakly singular point such that $|s(O)| + |\nabla s(O)| > 0$, then v^{∞} cannot vanish identically. Further, the wave field v cannot be analytically continued from $B_R \setminus \overline{D}$ to $B_{\epsilon}(O)$ for any $\epsilon > 0$.

Theorem 1.3 (Determination of source term). Assume that D and \mathfrak{n} are both known in advance and that $O \in \partial D$ is a weakly singular point. Then

- (i) The far-field pattern v^{∞} uniquely determines the values of s and ∇s at O.
- (ii) Suppose additionally that the source term s(x) satisfies the elliptic equation

$$\Delta s(x) + A(x) \cdot \nabla s(x) + b(x)s(x) = 0 \text{ on } \overline{D}, \qquad (1.4)$$

where $A(x) \in (L^{\infty}(B_R))^2$ and $b(x) \in L^{\infty}(B_R)$ are given functions that are realanalytic around O. Then s(x) can be uniquely determined by v^{∞} .

The admissible source functions satisfying (1.4) possess the property that the lowest order Taylor expansion at O is harmonic (see [19]), that is, for some $N \in \mathbb{N}_0$,

$$s(x) = r^N \left(A \cos(N\theta) + B \sin(N\theta) \right) + \mathcal{O}(r^{N+1}), \quad |x| \to 0, \ x \in B_{\epsilon}(O).$$

In particular, the case that $s|_{\overline{D}} \equiv s_0 \in \mathbb{C}$ is covered. For such kind of sources, it was proved in [19, Lemma 2.3] (see also [15, Appendix]) that solutions to the inhomogeneous Laplace equation $\Delta u = s$ in a sector cannot have vanishing Cauchy data on the boundary. Theorems 1.2 and 1.3 have generalized the results of [3,19] for planar corners to the case of arbitrarily weakly singular points (in the sense of Definition 1.1), under the analytical assumptions imposed on n and s. Without these a priori assumptions, one can prove uniqueness by using multi-frequency near/far field data; we refer to [1,13] for the uniqueness proof in a homogeneous background medium and to [2,10] for increasing stability estimates in terms of the bandwidth of frequencies.

1.2. Absence of non-scattering energies

Let $D \subset \mathbb{R}^2$ be a bounded penetrable scatterer embedded in a homogeneous isotropic background medium. The acoustic properties of D can be characterized by the refractive index function $q \in L^{\infty}(\mathbb{R}^2)$ such that $q \equiv 1$ in D^e after some normalization. Hence the contrast function 1 - q is compactly supported in D. Assume that a time-harmonic non-vanishing incoming wave u^{in} is incident onto D, which is governed by the Helmholtz equation $(\Delta + \kappa^2)u^{in} = 0$ at least in a neighborhood of D. For instance, u^{in} is allowed to be a plane wave, a Herglotz wave function or a point source wave emitting from some position in $\mathbb{R}^2 \setminus \overline{D}$. The wave propagation of the total field $u = u^{in} + u^{sc}$ is then modeled by the Helmholtz equation

$$\Delta u + \kappa^2 q \, u = 0 \quad \text{in} \quad \mathbb{R}^2$$

At infinity, the perturbed scattered field u^{sc} is supposed to fulfill the Sommerfeld radiation condition (1.3). The unique solvability of the above medium scattering problem in $H^2_{loc}(\mathbb{R}^2)$ is well known (see e.g., [12, Chapter 8]). We suppose that q is real-analytic on \overline{D} , that is, there exists a real-analytic function Q defined in a neighborhood of D such that $Q|_{\overline{D}} = q$. Let $O \in \partial D$ be a weakly singular point defined by Definition 1.1, where the boundary around O is locally parameterized by the function f. We suppose that $|q(O) - 1| + |\partial_1 q(O)| > 0$ because of the medium discontinuity across the interface. For instance, $q(x) = q_0 + q_1 x_1 + q_2 x_2$ on \overline{D} where $q_0, q_1, q_2 \in \mathbb{R}$ satisfying $|q_0 - 1| + |q_1| > 0$. This covers at least the piece-wise constant case that $q|_{\overline{D}} \equiv q_0 \neq 1$. However, we remark that the condition $|\partial_1 q(O)| \neq 0$, which depends on a suitable parameterization of the boundary, cannot be replaced by $|\nabla q(O)| \neq 0$ due to technical reasons. We shall prove that

Theorem 1.4 (Weakly singular points always scatter). The penetrable scatterer $D \subset \mathbb{R}^2$ scatters every incoming wave, if ∂D contains at least one weakly singular point O (see Definition 1.1). Further, u cannot be analytically continued from $\mathbb{R}^2 \setminus \overline{D}$ to $B_{\epsilon}(O)$ for any $\epsilon > 0$.

As a by-product of the proof of Theorem 1.4, we get a local uniqueness result to the shape identification with a single incoming wave.

Theorem 1.5. Let D_j (j = 1, 2) be two penetrable scatterers in \mathbb{R}^2 with the analytical potential functions q_j , respectively. If ∂D_2 differs from ∂D_1 in the presence of a weakly singular point lying on the boundary of the unbounded component of $\mathbb{R}^2 \setminus \overline{(D_1 \cup D_2)}$, then the far-field patterns corresponding to (D_j, q_j) incited by any non-vanishing incoming wave cannot coincide.

Here we mention the connection of Theorems 1.4 and 1.5 with a cloaking device. The latter always leads to vanishing observation data and is closely related to uniqueness in

inverse scattering. It follows from Theorem 1.4 that a cloaking device cannot be designed by homogeneous and isotropic medium with a weakly singular point lying the boundary surface. There are essential difficulties in our attempt to prove the global uniqueness with a single far-field pattern. To the best of our knowledge, such kind of global uniqueness for shape identification remains open for a long time, since Schiffer's first result using infinitely many plane waves in 1967 (see [27]). Theorem 1.5 has partly answered this open question.

The second assertions in Theorems 1.2 and 1.4 imply that, the wave field must be "singular" (that is, non-analytic) at a weakly singular point. Excluding the possibility of analytical extension turns out to be helpful in designing non-iterative inversion algorithms for locating planar corners; see e.g., the enclosure method [21,22], the one-wave version of range test approach [25,26,18] and no-response test method [29,30,34] as well as the data-driven scheme recently prosed in [16,19]. Most of these inversion schemes can be interpreted as domain-defined sampling methods (or analytic continuation tests, see [31, Chapter 15] for detailed discussions), in comparison with the pointwise-defined sampling approaches such as Linear Sampling Method [7], Factorization Method [24] and Point Source Method [33] etc. Combining the ideas of [16,25,26] with our results, one may conclude that arbitrarily weakly singular points lying on the convex hull of D can be numerically reconstructed from the data of a single far-field pattern.

In our previous work [28], the analogue results to Theorems 1.5 and 1.4 were verified in a piece-wise constant medium where the locally parameterized boundary function ftakes the special form (cf. (1.1))

$$f(x_1) = \begin{cases} f_j^+ x_1^j, & -\epsilon/2 < x_1 \le 0, \\ f_n^- x_1^n, & 0 \le x_1 < \epsilon/2, \end{cases} \quad j, n \in \mathbb{N}_0, \quad f_j^+, f_n^- \in \mathbb{R}, \end{cases}$$

with the conditions

$$j, n \ge 2, \quad (f_j^+, j) \ne (f_n^-, n), \quad (f_j^+)^2 + (f_n^-)^2 \ne 0.$$

Obviously, the weakly singular points and potential functions considered in this paper are more general than those in [28]. In fact, the mathematical techniques and algebraic calculations in the present paper are more subtle and intricate than [28].

For strongly singular corners [15,20], the smoothness of the potential function can be even weakened to be Hölder continuous with a lower contrast to the background medium (that is, 1 - q is C^k -smooth at O for some $k \ge 2$). Using additionally involved arguments, our approach can also handle the lower contrast case. However, we only consider the higher contrast medium fulfilling the condition $|q(O) - 1| + |\partial_1 q(O)| > 0$, since the emphasis of this paper is placed upon treating interfaces with weakly singular points of arbitrarily order $m \ge 2$.

In the recent article [8], it is revealed that in \mathbb{R}^n (n = 2, 3), if the Lipschitz boundary ∂D processes a non-analytic point O and if q is analytic in a neighborhood of O, then

the object D scatters the incoming wave u^{in} , provided that $(q(O) - 1)u^{in}(O) \neq 0$. The authors have also proved the same result under a weaker regularity assumption on q $(C^{m,\alpha}$ -smooth) but with a strong regularity assumption on ∂D $(C^{m+1,\alpha}$ -smooth) near x_0 . The approach in [8] relies on the free boundary method. Such a method has been also employed in [35] to show that penetrable scatterers with real-analytic boundaries admit an incident wave such that it doesn't scatter. Under the non-vanishing condition of the incident wave, a necessary condition on a boundary point was derived for the nonscattering phenomena. In comparison with the free boundary method, our approach does not rely on the non-vanishing condition imposed on the incident wave and the contrast q-1. In fact, we will show in Lemma 2.2 that all coefficients in the Taylor expansion of the incident field at a boundary singular point must vanish, if the corresponding far-field pattern vanishes. Hence, under the strong assumption that $u^{in}(O) \neq 0$ one can easily get a contradiction and our arguments can be significantly simplified. This explains why our approach extends to more general incident waves. Our results illustrate that piecewise analytic penetrable scatterers (at least C^1 -smooth but not C^{∞} -smooth) scatter any incoming waves, under the analytic assumption on q together with the medium discontinuity assumption $|q-1| + |\partial_1 q| > 0$ at the weakly singular point. Moreover, we establish a local uniqueness result for shape reconstruction with a single incoming wave. In comparison with the existing works, our approach is rather elementary, since it involves algebraic computations only.

The remaining part is organized as follows. Our main efforts will be spent on an analytical approach to the proof of Theorem 1.4 in Section 2. This also yields the local uniqueness result of Theorem 1.5. In Section 3, we shall adapt this approach to prove Theorems 1.2 and 1.3. The proofs of some important Lemmata will be given in the Appendix.

2. Weakly singular points always scatter

2.1. Proofs of Theorems 1.4 and 1.5

This section is devoted to the proofs of Theorems 1.4 and 1.5 when the penetrable scatterer ∂D contains a weakly singular point on the boundary. For this aim, we need to generalize the Cauchy-Kovalevski theorem for the Helmholtz equation to a piecewise analytic domain.

Lemma 2.1. Let D be a domain in \mathbb{R}^2 and suppose that the boundary ∂D in an ϵ -neighborhood of $O \in \partial D$ can be represented by $\Gamma = \{(x_1, f(x_1)) : x_1 \in (-\epsilon/2, \epsilon/2)\},$ where f is given by (1.1). Let \tilde{u} satisfy

$$\begin{aligned} \Delta \widetilde{u} + \widetilde{q}(x)\widetilde{u} &= 0 \quad in \quad D \cap B_{\epsilon}, \\ \widetilde{u} &= \widetilde{q}_0, \ \partial_{\nu}\widetilde{u} = \widetilde{q}_1 \quad on \quad \Gamma, \end{aligned}$$

where $\tilde{q} = \tilde{Q}|_{\overline{D}}, \tilde{g}_0 = \tilde{G}_0|_{\Gamma}, g_1 = \tilde{G}_1|_{\Gamma}$ with \tilde{Q}, \tilde{G}_0 and \tilde{G}_1 being analytic in B_{ϵ} . Then, there exists $\epsilon_1 \in (0, \epsilon)$ such that \tilde{u} can be extended analytically from $\overline{D} \cap B_{\epsilon_1}$ to B_{ϵ_1} and the extended function \tilde{u}_1 satisfies that

$$\Delta \widetilde{u}_1 + Q(x)\widetilde{u}_1 = 0 \quad in \quad B_{\epsilon_1}.$$

Proof. By the definition of Γ , we may extend one of its analytic components to a welldefined analytic function over the interval $(-\epsilon_1/2, \epsilon_1/2)$ for some $\epsilon_1 \in (0, \epsilon)$ sufficiently small. Define $\Gamma_1 := \{(x_1, f^+(x_1)) : x_1 \in (-\epsilon_1/2, \epsilon_1/2)\}$ with

$$f^+(x_1) = \sum_{n \in \mathbb{N}_0} \frac{f_n^+}{n!} x_1^n, \quad -\epsilon_1/2 < x_1 \le \epsilon_1/2.$$

Here, $\{f_n^+\}_{n \in \mathbb{N}_0}$ is given by (1.1). By the Cauchy-Kovalevski theorem (see e.g. [23, Chapter 3.3]), the Cauchy problem of the Helmholtz equation

$$\begin{split} &\Delta \widetilde{u}_1 + \widetilde{Q}(x) \widetilde{u}_1 = 0 & \text{in } B_{\epsilon_1}, \\ &\widetilde{u}_1 = \widetilde{G}_0|_{\Gamma_1}, \ \partial_{\nu} \widetilde{u}_1 = \widetilde{G}_1|_{\Gamma_1} & \text{on } \Gamma_1 \end{split}$$

admits only a unique analytic solution \tilde{u}_1 . Note that

$$\Delta(\widetilde{u}_1 - \widetilde{u}) + \widetilde{q}(x)(\widetilde{u}_1 - \widetilde{u}) = 0 \quad \text{in} \quad D \cap B_{\epsilon_1},$$

$$\widetilde{u}_1 = \widetilde{u}, \quad \partial_{\nu}\widetilde{u}_1 = \partial_{\nu}\widetilde{u}, \qquad \text{on} \quad \Gamma^+ \cap B_{\epsilon_1}.$$

where $\Gamma^+ = \{(x_1, f(x_1)) \in \Gamma : -\epsilon/2 < x_1 < 0\}$. Then, by Holmgren's theorem, it can be deduced that $\tilde{u}_1(x) = \tilde{u}(x)$ for $x \in D \cap B_{\epsilon_1}$. Therefore, \tilde{u}_1 can be considered as an analytical extension of \tilde{u} from $\overline{D} \cap B_{\epsilon_1}$ to B_{ϵ_1} . The proof of this lemma is thus complete. \Box

Since the Helmholtz equation remains invariant by coordinate translation and rotation, we can always suppose without loss of generality that the weakly singular point coincides with the origin. Assume that the boundary ∂D in an ϵ -neighborhood of O can be represented by $\Gamma = \{(x_1, f(x_1)) : x_1 \in (-\epsilon/2, \epsilon/2)\}$, where the function f is given by (1.1). Assuming that u^{sc} vanishes in D^e , we shall derive a contradiction. Across the interface ∂D , we have the continuity of the total field and its normal derivative,

$$u^+ = u^-, \quad \partial_\nu u^+ = \partial_\nu u^- \quad \text{on } \partial D.$$
 (2.1)

Here the superscripts $(\cdot)^{\pm}$ stand for the limits taken from outside and inside, respectively, and $\nu \in \mathbb{S}$ is the unit normal on ∂D pointing into D^e . Since $u^{sc} = 0$ in D^e , the Cauchy data of u on Γ coincide with those of u^{in} , which are real-analytic since the incoming wave fulfills the Helmholtz equation near D. Observing the fact that $q = Q|_{\overline{D}}$ is analytic



Fig. 1. Illustration of the piecewise analytic interface $\Gamma \subset \mathbb{R}^2$ which contains a weakly singular point at O = (0, 0).

on \overline{D} and that Γ is piecewise analytic, applying Lemma 2.1, one may analytically extend u from $\overline{D} \cap B_{\epsilon}$ to a small neighborhood of O in $D^e \cap B_{\epsilon}$. For notational convenience, we still denote the extended domain by B_{ϵ} and the extended function by u, satisfying the Helmholtz equation

$$\Delta u + \kappa^2 Q(x)u = 0 \quad \text{in} \quad B_{\epsilon}.$$

In the subsequent sections we take $\epsilon = 1$ for simplicity (see Fig. 1). Using the transmission conditions (2.1) together with $u^{sc} \equiv 0$ in D^e , we deduce that

$$\begin{cases} \Delta w_j + q_j(x)w_j = 0, & \text{in } B_1, \quad j = 1, 2, \\ w_1 = w_2, \quad \partial_{\nu}w_1 = \partial_{\nu}w_2 & \text{on } \Gamma, \end{cases}$$
(2.2)

where

$$w_1 = u^{in}, \quad w_2 = u, \qquad q_1(x) \equiv \kappa^2, \quad q_2(x) = \kappa^2 Q(x).$$
 (2.3)

We shall prove

Lemma 2.2. Let q_1 and q_2 be real-analytic functions defined in B_1 . Suppose that $w_j \in H^2(B_1)$ (j = 1, 2) are solutions to (2.2) and $O \in \Gamma$ is a weakly singular point with the local parametrization of the form (1.1). If

$$|(q_1 - q_2)(O)| + |\partial_1(q_1 - q_2)(O)| > 0$$
(2.4)

then $w_1 = w_2 \equiv 0$ in B_1 .

Lemma 2.2 implies that the Cauchy data of two Helmholtz equations cannot coincide on a piecewise analytic curve with a weakly singular point, if the analytical potentials involved fulfill the condition (2.4). The result of Lemma 2.2 is not valid if $q_1 \equiv q_2$ near O. It also implies that, solutions to the Helmholtz equation $\Delta w_1 + q_1(x)w_1 = 0$ in $B_1^+ := \{x \in B_1 : x_2 > f(x_1)\}$ (see Fig. 1) cannot be analytically continued into B_1 , if the Cauchy data of w_1 coincide with those of w_2 on Γ . Hence, Lemma 2.2 gives a sufficient condition of the boundary under which solutions to the Helmholtz equation admit no analytical extension. This is in contrast with the Cauchy-Kowalevski theorem (see e.g., [23, Chapter 3.3]) which guarantees a locally analytical extension of analytic solutions if both the Cauchy data and boundary surface are analytic. It seems that this local property of the Helmholtz equation also extends to other elliptic equations such as the Lamé system.

Based on Lemma 2.2, we can readily prove Theorems 1.4 and 1.5.

Proof of Theorems 1.4 and 1.5. Let $O \in \partial D$ be a weakly singular point. We first note that the jump condition (2.4) applies to the potentials given in (2.3), since $|q(O) - 1| + |\partial_1 q(O)| > 0$. To prove the first assertion of Theorem 1.4, we suppose that the far-field pattern produced by some non-vanishing incoming wave u^{in} vanishes identically. By Rellich's lemma (see e.g., [12, Theorem 2.13, Chapter 2.5]), the scattered field u^{sc} must vanish identically in $\mathbb{R}^2 \setminus \overline{D}$. Hence, the transmission conditions for the total field u can be reduced to

$$u^- = (u^{in})^+, \quad \partial_\nu u^- = \partial_\nu (u^{in})^+ \quad \text{on} \quad \partial D.$$

By the regularity assumptions on q and ∂D , one can get the system (2.2)-(2.3) around any weakly singular point of ∂D . As a consequence of Lemma 2.2, we obtain $u^{in} \equiv 0$ in a small neighborhood of the weakly singular point. By the unique continuation, u^{in} vanishes identically in \mathbb{R}^2 , which contradicts our assumption. Hence, an analytical potential with a weakly singular point lying on the boundary of the contrast function's support always scatters. If the total field u can be analytically continued from $\mathbb{R}^2 \setminus \overline{D}$ to $B_{\epsilon}(O)$ for some $\epsilon > 0$, the extended solution, which we denote by w_1 , should satisfy the following Helmholtz equation

$$\Delta w_1 + \kappa^2 w_1 = 0 \quad \text{in} \quad B_{\epsilon}(O).$$

Note that the total field fulfills the same equation in the exterior of \overline{D} . Then one can get the same system as (2.2), where w_1 is now replaced by the extension of u. By Lemma 2.2 we get $u \equiv 0$, implying that u^{sc} can be extended to an entire radiating solution to the Helmholtz equation. Hence we obtain the vanishing of u^{sc} and thus also the vanishing of u^{in} , which is impossible. This proves the second assertion of Theorem 1.4 by applying Lemma 2.2. The local uniqueness result of Theorem 1.5 follows directly from the second assertion of Theorem 1.4.

Remark 2.3. Lemma 2.2 does not hold true if the curve Γ is analytic at O. Counterexamples can be constructed when Γ is a line segment or a circle (see [15, Remark 3.3], [28, Section 4] and [11]). We conjecture that Theorem 1.4 remains valid even under the following weaker assumptions:

Conjecture: Let $\Gamma := \{x_2 = f^{\pm}(x_1), x_1 \leq 0\}$ where f^{\pm} are real-analytic functions for $x_1 \leq 0$. Suppose that Γ is C^{∞} -smooth but not real-analytic at O and that $q_1 \neq q_2$ are two (complex) constants. If w_1 and w_2 are solutions to

$$\begin{cases} \Delta w_1 + q_1 w_1 = 0, & \text{in } B_1, \\ \Delta w_2 + q_2 w_2 = 0, & \text{in } B_1^+, \\ w_1 = w_2, \quad \partial_\nu w_1 = \partial_\nu w_2 & \text{on } \Gamma. \end{cases}$$

Then it holds that $w_1 = w_2 \equiv 0$.

In the present paper we consider only a piecewise analytic interface which is not C^{∞} smooth at O. In general, each component of the piecewise analytic curve defined in the above conjecture cannot be analytically continued across $O \in \Gamma$, which is in contrast to the singular point defined by (1.1). Hence, the proof for C^{∞} -smooth boundaries with a non-analytical point requires novel mathematical arguments.

2.2. Preliminary lemmata

The proof of Lemma 2.2 will be given in Subsections 2.3 and 2.4. In this subsection we prepare several import Lemmata to be used in the proof of Lemma 2.2.

Setting $w := w_1 - w_2$, it is easy to obtain

$$\Delta w + q_1 w = -(q_1 - q_2) w_2 \quad \text{in} \quad B_1 \tag{2.5}$$

subject to the vanishing Cauchy data

$$w = \partial_{\nu} w = 0 \quad \text{on } \Gamma. \tag{2.6}$$

It follows from (2.6) that

$$h(x_1) := w(x_1, f(x_1)) = 0, (2.7)$$

$$g(x_1) := \partial_2 w(x_1, f(x_1)) = 0,$$
 (2.8)

for all $x_1 \in (-1/2, 1/2)$.

Since the potentials q_j are real-analytic, the solutions w_j and w are all analytic functions in B_1 . Hence, w and w_2 can be expanded into the Taylor series

$$w(x) = \sum_{i,j \ge 0} \frac{a_{i,j}}{i!j!} x_1^i x_2^j, \qquad w_2(x) = \sum_{i,j \ge 0} \frac{b_{i,j}}{i!j!} x_1^i x_2^j, \quad x = (x_1, x_2) \in B_1.$$
(2.9)

The Taylor expansion of $\partial_2 w$ can be written as

$$\partial_2 w(x_1, x_2) = \sum_{i,j \ge 0} \frac{a_{i,j+1}}{i!j!} x_1^i x_2^j, \qquad x = (x_1, x_2) \in B_1.$$
(2.10)

The above Taylor expansions in the Cartesian coordinate system turn out to be convenient in dealing with weakly singular points (see also [28]). The corresponding expansions in polar coordinates were used in [14] for treating planar corners. Inserting (1.1) into (2.9) and (2.10), we may rewrite the functions h and g as

$$h(x_1) = \sum_{i,j \in \mathbb{N}_0} \frac{a_{i,j}}{i!\,j!} x_1^i [f(x_1)]^j = \begin{cases} \sum_{l \in \mathbb{N}_0} \frac{h_l^+}{l!} x_1^l, & -1/2 < x_1 \le 0, \\ \sum_{l \in \mathbb{N}_0} \frac{h_l^-}{l!} x_1^l, & 0 \le x_1 < 1/2, \end{cases}$$
(2.11)

and

$$g(x_1) = \sum_{i,j \in \mathbb{N}_0} \frac{a_{i,j+1}}{i! \, j!} x_1^i [f(x_1)]^j = \begin{cases} \sum_{l \in \mathbb{N}_0} \frac{g_l^+}{l!} x_1^l, & -1/2 < x_1 \le 0, \\ \sum_{l \in \mathbb{N}_0} \frac{g_l^-}{l!} x_1^l, & 0 \le x_1 < 1/2, \end{cases}$$
(2.12)

respectively. It then follows from (2.7) and (2.8) that

$$h_l^{\pm} = g_l^{\pm} = 0 \quad \text{for all} \quad l \in \mathbb{N}_0.$$

$$(2.13)$$

Lemma 2.2 will be proved with the help of (2.5), (2.9), (2.13) and the following identity

$$\Delta \Delta w + q_1 \Delta w + 2\nabla q_1 \cdot \nabla w + \Delta q_1 w$$

= $-(q_1 - q_2)q_2w_2 + 2\nabla (q_1 - q_2) \cdot \nabla w_2 + \Delta (q_1 - q_2)w_2$ (2.14)

in B_1 , which was obtained by taking Δ on both sides of (2.5). In fact, from these relations we shall deduce through an induction argument and the weekly singularity at O (more precisely, $f_m^+ \neq f_m^-$) that $a_{i,j} = b_{i,j} = 0$ for all $i, j \in \mathbb{N}_0$, which imply the vanishing of w_1 and w_2 by analyticity.

Let $m \in \mathbb{N}$ $(m \ge 2)$ be the order of the singular point O specified in Definition 1.1. We can always find a number $n \in \mathbb{N}, 2 \le n \le m$ such that

$$f_l = 0$$
 for all $0 \le l < n;$ $f_n \ne 0,$ if $n < m.$ (2.15)

That is, f_n is the first non-vanishing coefficient appearing in the expansion of f around zero. To prove Lemma 2.2, we first consider the case of n < m. If n = m, the proof can be proceeded analogously (see Remark 2.7). Since $2 \le n < m$ and $m \ge 2$, we have

$$x_{2} = f(x_{1}) = \sum_{j=n}^{m-1} \frac{f_{j}}{j!} x_{1}^{j} + \begin{cases} \sum_{j \ge m} \frac{f_{j}^{+}}{j!} x_{1}^{j}, & \text{if } x_{1} < 0, \\ \sum_{j \ge m} \frac{f_{j}^{-}}{j!} x_{1}^{j}, & \text{if } x_{1} > 0, \end{cases} \qquad f_{m}^{+} \neq f_{m}^{-}.$$
(2.16)

The first lemma describes the relation between the coefficients h_l^{\pm} , g_l^{\pm} and $a_{i,j}$ for $0 \leq l < 3n - 1$. Recall from and (2.11) and (2.16) that

$$h(x_1) = \sum_{i,j \in \mathbb{N}_0} \frac{a_{i,j}}{i!\,j!} x_1^i \left(\sum_{l=n}^{m-1} \frac{f_l}{l!} x_1^l + \sum_{l=m}^{\infty} \frac{f_l^{\pm}}{l!} x_1^l \right)^j$$
$$= \sum_{l \in \mathbb{N}_0} \frac{h_l^{\pm}}{l!} x_1^l \quad \text{for} \quad x_1 \leq 0.$$
(2.17)

Lemma 2.4.

(i) For $0 \le l \le n-1$, we have

$$h_l^{\pm} = \frac{a_{l,0}}{l!}, \quad g_l^{\pm} = \frac{a_{l,1}}{l!}.$$
 (2.18)

(ii) For $n \leq l \leq 2n - 1$, we have

$$h_l^{\pm} = \frac{a_{l,0}}{l!} + \sum_{j=0}^{l-n} \frac{a_{l-n-j,1}}{(l-n-j)!} \frac{f_{j+n}^{\pm}}{(j+n)!},$$
(2.19)

$$g_l^{\pm} = \frac{a_{l,1}}{l!} + \sum_{j=0}^{l-n} \frac{a_{l-n-j,2}}{(l-n-j)!} \frac{f_{j+n}^{\pm}}{(j+n)!}.$$
 (2.20)

(iii) For $2n \leq l \leq 3n-1$, we have

$$h_{l}^{\pm} = \frac{a_{l,0}}{l!} + \sum_{j=0}^{l-n} \frac{a_{l-n-j,1}}{(l-n-j)!} \frac{f_{j+n}^{\pm}}{(j+n)!} + \sum_{j=0}^{l-2n} \frac{a_{l-2n-j,2}}{(l-2n-j)!} \left(\sum_{i=0}^{j} \frac{f_{i+n}^{\pm} f_{j-i+n}^{\pm}}{(i+n)! (j-i+n)!} \right)$$
(2.21)

and g_l^{\pm} takes the same form as h_l^{\pm} with $a_{\cdot,j}$ replaced by $a_{\cdot,j+1}$.

The above lemma follows directly by equating the coefficients for x_1^l on both sides of (2.17) and using the fact that $[f(x_1)]^j = O(x_1^{nj})$. Write the index l = i + nj for $i, j, n \in \mathbb{N}_0$. Then, the relation $0 \le l \le n - 1$ implies j = 0, i = l in the first assertion; the relation $n \le l \le 2n - 1$ implies j = 0, i = l or j = 1, i = l - n in the second assertion; the relation $2n \le l \le 3n - 1$ implies j = 0, i = l, or j = 1, i = l - n, or j = 2, i = l - 2nin the third assertion. These results will be used in justifying the initial steps of the induction hypothesis. We will express g_l^{\pm} and h_l^{\pm} for some other l in the appendix. In our induction arguments, we need the following definition and lemma.

Definition 2.5. Let *n* be given by (2.15). For $a \in \mathbb{N}_0$ and $\alpha \in \{0, 1, 2\}$, it is said that the pair $(i, j) \in \mathbb{N}_0 \times \mathbb{N}_0$ with $i \leq a$ and $j \geq \alpha$ belongs to the index set Υ^a_{α} if either $(i, j) = (a, \alpha)$ or there exists some $d \in \mathbb{N}$ and two sequences of positive integers $\{i_k\}_{k=1}^d, \{j_k\}_{k=1}^d$ with $i_k \geq n$ such that

$$i + \sum_{k=1}^{d} i_k j_k = a, \qquad \sum_{k=1}^{d} j_k = j - \alpha.$$
 (2.22)

Lemma 2.6. Suppose that the coefficients in the Taylor expansion of w (see (2.9)) fulfill the relations

$$a_{i,j} = 0$$
 if $i + jn \le k - 1 + 3n$ or $i + j \le k + 2, j > 3,$ (2.23)

for some $k \in \mathbb{N}$. Then the relation $g(x_1) \equiv 0$ for all $x_1 \in (-1/2, 1/2)$ (see (2.12) for the definition of q) implies that

$$\frac{\left(f_m^{\pm}\right)^2}{\left(m!\right)^2}\frac{3a_{k,3}}{k!3!} + \frac{f_m^{\pm}}{m!}2D_{k,1} + D_{k,2} = 0.$$
(2.24)

The relation $h(x_1) = 0$ for all $x_1 \in (-1/2, 1/2)$ implies that

$$\frac{(f_m^{\pm})^3}{(m!)^3} \frac{a_{k,3}}{k!3!} + \frac{(f_m^{\pm})^2}{(m!)^2} D_{k,1} + \frac{f_m^{\pm}}{m!} D_{k,2} + D_{k,3} = 0.$$
(2.25)

Here $D_{k,l} \in \mathbb{C}$ (l = 1, 2, 3) depends on $a_{i,j}$ with $(i, j) \in \Upsilon_{3-l}^{lm+k}$ and only on the coefficients f_j of $f(x_1)$ with j < m.

The proof of Lemma 2.6 will be postponed to the appendix. To prove Lemma 2.2when n < m, we need to consider two cases:

- Case (i): $q_1(O) \neq q_2(O)$; Case (ii): $q_1(O) = q_2(O), \partial_1 q_1(O) \neq \partial_1 q_2(O).$
- 2.3. Proof of Lemma 2.2 in Case (i): $q_1(O) \neq q_2(O)$

For simplicity, we shall divide our proof into four steps through the induction argument. Recall again from (2.13) that h_l^{\pm} and g_l^{\pm} vanish for all $l \in \mathbb{N}_0$. **Step 1**: First, it follows from the expressions of h_l^{\pm} and g_l^{\pm} for $0 \leq l \leq n-1$ (see

(2.18)) that

$$a_{i,0} = 0, \qquad 0 \le i \le n-1$$

and

$$a_{i,1} = 0, \qquad 1 \le i \le n - 1.$$
 (2.26)

Inserting (2.26) into (2.19) yields

$$a_{i+n,0} = 0, \qquad 0 \le i \le n-1.$$

14

To summarize above, we get

$$a_{i,j} = 0, \qquad i + jn \le 2n - 1.$$

Step 2: We shall prove $a_{i,j} = 0, 2n \le i + jn \le 3n - 1$ and $b_{0,0} = 0$.

Using the results of Step 1 and the expression of g (see (2.12)), we get

$$0 = \sum_{i \ge n} \frac{a_{i,1}}{i!} x_1^i + \left(\sum_{i \ge 0} \frac{a_{i,2}}{i!} x_1^i \right) \left(\sum_{l=n}^{m-1} \frac{f_l}{l!} x_1^l + \sum_{l=m}^{\infty} \frac{f_l^{\pm}}{l!} x_1^l \right) + \cdots$$
 (2.27)

Equating the coefficients of x_1^{γ} with $m \leq \gamma \leq n + m - 1$, we have

$$\eta_{\gamma} + \frac{1}{(\gamma - m)!} \frac{f_m^+}{m!} a_{\gamma - m, 2} = \eta_{\gamma} + \frac{1}{(\gamma - m)!} \frac{f_m^-}{m!} a_{\gamma - m, 2},$$

where η_{γ} depends on $a_{i,j}$ and f_l with l < m. Utilizing the condition that $f_m^+ \neq f_m^-$, we have

$$a_{\gamma-m,2} = 0$$
 for any $m \le \gamma \le n+m-1$,

implying that $a_{l,2} = 0$ for all $0 \le l \le n-1$. Now, using (2.20) we get $a_{l,1} = 0$ for all $n \le l \le 2n-1$. Together with (2.21), this gives $a_{l,0} = 0$ for all $2n \le l \le 3n-1$. Now we conclude that $a_{i,j} = 0$ for all i, j such that $2n \le i + jn \le 3n-1$.

The results in the first two steps give rise to $a_{0,0} = a_{2,0} = a_{0,2} = 0$, implying that $w(O) = \Delta w(O) = 0$. Since $q_1(O) \neq q_2(O)$, it is deduced from (2.5) that $w_2(O) = 0$, that is,

$$b_{0,0} = 0. (2.28)$$

Step 3: In this step, we will prove

$$a_{i,j} = 0 \quad \text{if} \quad 3n \le i + jn \le 3n + 1 \quad \text{or} \quad i + j = 4, b_{i,j} = 0 \quad \text{if} \quad 1 \le i + j \le 2.$$

$$(2.29)$$

We first consider the case of i+nj = 3n. It is deduced from Steps 1-2 that the coefficients $a_{i,j}$ satisfy the assumption of Lemma 2.6 with k = 0. Taking k = 0 in (2.24) and (2.25), we obtain

$$(f_m^{\pm})^3 \frac{a_{0,3}}{3!(m!)^3} + \frac{(f_m^{\pm})^2}{(m!)^2} D_{0,1} + \frac{f_{\pm}^m}{m!} D_{0,2} + D_{0,3} = 0, \qquad (2.30)$$

$$(f_m^{\pm})^2 \frac{3a_{0,3}}{3!(m!)^2} + 2\frac{f_m^{\pm}}{m!} D_{0,1} + D_{0,2} = 0.$$
(2.31)

We deduce from (2.31) and (2.30) that

$$(f_m^+)^2 \frac{3a_{0,3}}{3!(m!)^2} + 2\frac{f_m^+}{m!} D_{0,1} = (f_m^-)^2 \frac{3a_{0,3}}{3!(m!)^2} + 2\frac{f_m^-}{m!} D_{0,1},$$
(2.32)

$$2(f_m^+)^3 \frac{a_{0,3}}{3!(m!)^3} + \frac{(f_m^+)^2}{(m!)^2} D_{0,1} = 2(f_m^-)^3 \frac{a_{0,3}}{3!(m!)^3} + \frac{(f_m^-)^2}{(m!)^2} D_{0,1}.$$
 (2.33)

Combining (2.32) and (2.33) gives the algebraic equations for $a_{0,3}$ and $D_{0,1}$,

$$(f_m^+ + f_m^-)\frac{3a_{0,3}}{3!m!} + 2D_{0,1} = 0,$$

$$\frac{2a_{0,3}}{3!m!}((f_m^+)^2 + (f_m^-)^2 + f_m^+f_m^-) + D_{0,1}(f_m^+ + f_m^-) = 0,$$
 (2.34)

which can be written in the matrix form

$$M\begin{bmatrix}\frac{a_{0,3}}{3!m!}\\D_{0,1}\end{bmatrix} = 0, \quad M =: \begin{bmatrix}3(f_m^+ + f_m^-) & 2\\2((f_m^+)^2 + (f_m^-)^2 + f_m^+ f_m^-) & (f_m^+ + f_m^-)\end{bmatrix}.$$
 (2.35)

Since $|M| = -(f_m^+ - f_m^-)^2 \neq 0$, we obtain

$$a_{0,3} = 0. (2.36)$$

Now, the expression of g can be rephrased in $x_1 \leq 0$ as (cf. (2.27))

$$0 = \sum_{i \ge 2n} \frac{a_{i,1}}{i!} x_1^i + \left(\sum_{i \ge n} \frac{a_{i,2}}{i!} x_1^i \right) \left(\sum_{l=n}^{m-1} \frac{f_l}{l!} x_1^l + \sum_{l=m}^{\infty} \frac{f_l^{\pm}}{l!} x_1^l \right) \\ + \left(\sum_{i \ge 0} \frac{a_{i,3}}{i! \, 2!} x_1^i \right) \left(\sum_{l=n}^{m-1} \frac{f_l}{l!} x_1^l + \sum_{l=m}^{\infty} \frac{f_l^{\pm}}{l!} x_1^l \right)^2 + \cdots,$$

where we have used the results of Step 2. Making the difference for the coefficients of x_1^{n+m} , we get

$$\frac{a_{0,3}}{2!}\frac{f_n}{n!}\frac{f_m^+}{m!} + \frac{a_{n,2}}{n!2!}\frac{f_m^+}{m!} = \frac{a_{0,3}}{2!}\frac{f_n}{n!}\frac{f_m^-}{m!} + \frac{a_{n,2}}{n!2!}\frac{f_m^-}{m!}$$

Utilizing the fact $f_m^+ \neq f_m^-$, we get

$$a_{0,3}f_n + a_{n,2} = 0.$$

This together with (2.36) yields that

$$a_{n,2} = 0. (2.37)$$

Furthermore, by equating the coefficients of x_1^{2n} we get

$$\frac{a_{0,3}}{2!(n!)^2}(f_n)^2 + \frac{a_{n,2}}{(n!)^2}f_n + \frac{a_{2n,1}}{(2n)!} = 0.$$

On the other hand, equating the coefficients of x_1^{3n} in the expression of $h(x_1)$ leads to

$$\frac{a_{0,3}}{3!n!^3}(f_n)^3 + \frac{a_{n,2}}{2(n!)^3}(f_n)^2 + \frac{a_{2n,1}}{(2n)!n!}f_n + \frac{a_{3n,0}}{(3n)!} = 0.$$

Combining (2.36), (2.37) and the previous two identities leads to $a_{2n,1} = a_{3n,0} = 0$. This proves the first relations for $a_{i,j}$ with i + jn = 3n appearing in (2.29), i.e.,

$$a_{0,3} = a_{n,2} = a_{2n,1} = a_{3n,0} = 0. (2.38)$$

Recall from the first two steps that $a_{0,3} = a_{2,1} = a_{1,2} = 0$. Hence, $\partial_j \Delta w(O) = 0$ for j = 1, 2. Taking ∂_j to both sides of (2.5) and using the fact that $q_1(O) \neq q_2(O)$ and $w_2(O) = 0$, we get $\partial_j w_2(O) = 0$, or equivalently,

$$b_{1,0} = b_{0,1} = 0. (2.39)$$

Repeating the same arguments, one can prove for i + jn = 3n + 1 that

$$a_{1,3} = a_{n+1,2} = a_{2n+1,1} = a_{3n+1,0} = 0. (2.40)$$

This together $a_{l,0} = 0$ for $2n \le l \le 3n - 1$ and (2.38) yields that

$$a_{4,0} = a_{3,1} = a_{2,2} = a_{1,3} = 0. (2.41)$$

Equating the coefficients of the lowest order in (2.14) and using (2.28), (2.39), we readily obtain $a_{0,4} = 0$. Furthermore, we get $b_{0,2} = b_{1,1} = b_{2,0} = 0$ with the help of (2.5). This together with (2.38)-(2.41) gives (2.29).

Step 4: Induction arguments. We make the hypothesis that

$$a_{i,j} = 0 \quad \text{for all } (i,j) \in \mathbb{N}_0 \times \mathbb{N}_0 \text{ such that}$$

$$\begin{cases} i+jn \le p-1 & \text{if } j \le 3, \\ i+j \le p-3n+2, & \text{if } j \ge 4, \end{cases}$$

$$b_{i,j} = 0 \quad \text{for all } (i,j) \in \mathbb{N}_0 \times \mathbb{N}_0 \text{ such that } i+j \le p-3n \end{cases}$$
(2.42)

for some $p \ge 3n + 2$, $p \in \mathbb{N}$. Note that for p = 3n + 2, this hypothesis has been proved in steps 1-3. Now we need to prove the hypothesis with the index p replaced by p + 1. For this purpose, it suffices to check that

$$a_{i,j} = 0 \quad \text{for all } (i,j) \in \mathbb{N}_0 \times \mathbb{N}_0 \text{ such that}$$
$$\begin{cases} i+jn = p & \text{if } j \leq 3, \\ i+j = p - 3n + 3, & \text{if } j \geq 4, \end{cases}$$
(2.43)

$$b_{i,j} = 0$$
 for all $(i,j) \in \mathbb{N}_0 \times \mathbb{N}_0$ such that $i+j = p-3n+1$. (2.44)

For notational convenience, we introduce the set

$$I_p := \{(i,j) \in \mathbb{N}_0 \times \mathbb{N}_0 : i+jn = p\}.$$

By our assumption that n > 2, it holds for $(i_1, j_1), (i_2, j_2) \in I_p$ that

$$i_1 + j_1 > i_2 + j_2$$
, if $j_1 < j_2$.

Therefore, for $(i, j) \in I_p$, we have

$$i + j , if $j > 3$.$$

By the induction hypothesis (2.42), we get

$$a_{i,j} = 0$$
, for all $(i, j) \in I_p$, $j > 3$.

Furthermore, it follows from the induction hypothesis that the coefficients $a_{i,j}$ fulfill the assumption of Lemma 2.6 with k = p - 3n. Hence, setting k = p - 3n in (2.24) and (2.25) yields

$$0 = (f_m^{\pm})^3 \frac{a_{p-3n,3}}{(p-3n)!3!(m!)^3} + \frac{(f_m^{\pm})^2}{(m!)^2} D_{p-3n,1} + \frac{f_{\pm}^m}{m!} D_{p-3n,2} + D_{p-3n,3}, \quad (2.45)$$

$$0 = (f_m^{\pm})^2 \frac{3a_{p-3n,3}}{(p-3n)!3!(m!)^2} + 2\frac{f_m^{\pm}}{m!}D_{p-3n,1} + D_{p-3n,2}.$$
(2.46)

Similarly to the derivation of (2.34) and (2.36) in Step 3, using $f_m^+ \neq f_m^-$ we can get a linear algebraic system for $a_{p-3n,3}$ and $D_{p-3n,1}$ as follows:

$$M\begin{pmatrix} \frac{a_{p-3n,3}}{(p-3n)!3!m!}\\ D_{p-3n,1} \end{pmatrix} = 0,$$
(2.47)

where $M \in \mathbb{R}^{2 \times 2}$ is defined again by (2.35). The fact that $|M| \neq 0$ gives $a_{p-3n,3} = 0$. Inserting (1.1) into (2.8) and equating the coefficients of x_1^{p-2n+m} , we readily get

$$2\frac{3a_{p-3n,3}}{(p-3n)!3!}\frac{f_n}{n!}\frac{f_m^+}{m!} + \frac{2a_{p-2n,2}}{2(p-2n)!}\frac{f_m^+}{m!} = 2\frac{3a_{p-3n,3}}{(p-3n)!3!}\frac{f_n}{n!}\frac{f_m^-}{m!} + \frac{2a_{p-2n,2}}{2(p-2n)!}\frac{f_m^-}{m!}$$

This combined with $a_{p-3n,3} = 0$ and $f_m^+ \neq f_m^-$ yields

$$a_{p-3n,3} = a_{p-2n,2} = 0. (2.48)$$

Using the induction hypothesis and comparing the coefficients of x_1^p and x_1^{p-n} , respectively, it follows that

$$\frac{a_{p-3n,3}}{3!(p-3n)!} \frac{(f_n)^3}{(n!)^3} + \frac{a_{p-2n,2}}{2(p-2n)!} \frac{(f_n)^2}{(n!)^2} + \frac{a_{p-n,1}}{(p-n)!} \frac{f_n}{n!} + \frac{a_{p,0}}{(p)!} = 0,$$
(2.49)

$$\frac{3a_{p-3n,3}}{3!(p-3n)!}\frac{(f_n)^2}{(n!)^2} + \frac{2a_{p-2n,2}}{2(p-2n)!(n!)}\frac{f_n}{n!} + \frac{a_{p-n,1}}{(p-n)!} = 0.$$
 (2.50)

Combining (2.48), (2.49) and (2.50), we have

$$a_{p-3n,3} = a_{p-2n,2} = a_{p-n,1} = a_{p,0} = 0.$$
(2.51)

On the other hand, utilizing the fact that $n \ge 2$ and the induction hypothesis for $a_{i,j}$ with $j \le 3$, we get

$$a_{p-3n+1,2} = a_{p-3n+2,1} = a_{p-3n+3,0} = 0.$$
(2.52)

With the aid of (2.14), (2.52) and the induction hypothesis $b_{i,j} = 0, i + j \le p - 3n$, we readily get by equating the coefficients of $x_1^{i_1} x_2^{j_1}$, with $i_1 + j_1 = p - 3n - 1$ that

$$a_{i,j} = 0$$
, if $i+j = p-3n+3$, $j \ge 4$. (2.53)

This together with (2.5) gives $b_{i,j} = 0$ if i + j = p - 3n + 1.

By far we have proved all relations in (2.43) and (2.44). By induction, it holds that $a_{i,j} = b_{i,j} = 0$ for all $i, j \in \mathbb{N}_0$. The proof of case (i) is thus complete. \Box

2.4. Proof of Lemma 2.2 in Case (ii): $q_1(O) = q_2(O), \partial_1 q_1(O) \neq \partial_1 q_2(O)$

The proof in the second case can be carried out analogously to case (i). Below we sketch the proof by indicating the differences to case (i).

Step 1: Using the same arguments in the proof of case (i), we have $a_{i,j} = 0, i + jn \le 3n - 1$.

Step 2: Similar to the derivation of (2.38) in case (i), we can obtain $a_{0,3} = a_{n,2} = a_{2n,1} = a_{3n,0} = 0$. From (2.5), we get

$$\partial_1(q_1(O) - q_2(O))b_{0,0} = a_{3,0} = 0.$$

This together with the condition $\partial_1 q_1(O) \neq \partial_1 q_2(O)$ gives $b_{0,0} = 0$. Repeating this procedure, we could prove $a_{1,3} = a_{n+1,2} = a_{2n+1,1} = a_{3n+1,0} = 0$. Combining this with (2.5) yields that

$$(\partial_1(q_1(O) - q_2(O)))b_{1,0} = \frac{1}{2}a_{4,0} + \frac{1}{2}a_{2,2} = 0, (\partial_2(q_1(O) - q_2(O)))b_{1,0} + (\partial_1(q_1(O) - q_2(O)))b_{0,1} = a_{3,1} + a_{1,3} = 0, (\partial_2(q_1(O) - q_2(O)))b_{0,1} = \frac{1}{2}a_{0,4},$$

which imply $b_{1,0} = b_{0,1} = 0$. This together with (2.14) leads to $a_{0,4} = 0$. To summarize this step we obtain

$$a_{i,j} = 0, \quad 3n \le i + jn \le 3n + 1 \quad \text{or} \quad i + j = 4;$$

 $b_{i,j} = 0, \quad i + j \le 1.$

Step 3. In this step, we will adopt an induction argument similar to Step 4 of case (i). We make the same hypothesis for $a_{i,j}$ as before: $a_{i,j} = 0$ for all $i + jn \le p - 1, j \le 3$ and $i + j \le p - 3n + 2, j \ge 4$, where $p \ge 3n + 2, p \in \mathbb{N}_0$. However, we assume that $b_{i,j} = 0$, $i + j \le p - 3n - 1$, with an upper bound of i + j different from case (i). Our aim is to prove (2.43) and

$$b_{i,j} = 0, i+j = p - 3n. (2.54)$$

We remark that the relations in (2.43) can be proved in the same way as Step 3 of case (i). To prove (2.54), with the help of induction hypothesis, we conclude from (2.5) that

$$\frac{\left(\partial_1(q_1-q_2)(O)\right)}{(p_1-3)!}b_{p_1-3,0} = \frac{1}{(p_1-2)!}(a_{p_1,0}+a_{p_1-2,2}),$$

$$\frac{\left(\partial_2(q_1-q_2)(O)\right)}{(p_1-k_1-3)!k_1!}b_{p_1-k_1-3,k_1} + \frac{\left(\partial_1(q_1-q_2)(O)\right)}{(p_1-k_1-4)!(k_1+1)!}b_{p_1-k_1-4,k_1+1} \qquad (2.55)$$

$$=\frac{1}{(p_1-k_1-3)!(k_1+1)!}(a_{p_1-k_1-1,k_1+1}+a_{p_1-k_1-3,k_1+3}),$$
(2.56)

$$\frac{\left(\partial_2(q_1-q_2)(O)\right)}{(p_1-3)!}b_{0,p_1-3} = \frac{1}{(p_1-2)!}a_{2,p_1-2},$$

where $p_1 = p - 3n + 3$ and k_1, k_2 are two integers satisfying $0 \le k_1 \le (p_1 - 4), 0 \le k_2 \le (p_1 - 4)$. Analogously, combining with induction hypothesis and (2.14) gives that

$$\frac{2}{(p_1-4)!} \left(\left(\partial_1(q_1-q_2)(O) \right) b_{p_1-3,0} + \left(\partial_2(q_1-q_2)(O) \right) b_{p_1-4,1} \right) \\
= \frac{(a_{p_1,0}+2a_{p_1-2,2}+a_{p_1-4,4})}{(p_1-4)!}, \\
\frac{2}{(p_1-k_2-4)!k_2!} \left(\left(\partial_1(q_1(O)-q_2(O)) \right) b_{p_1-k_2-3,k_2} + \left(\partial_2(q_1(O)-q_2(O)) \right) b_{p_1-k_2-4,k_2+1} \right) \\
= \frac{1}{(p_1-k_2-4)!k_2!} (a_{p_1-k_2,k_2}+2a_{p_1-k_2-2,k_2+2}+a_{p_1-k_2-4,k_2+4}).$$
(2.57)

Further, using the similar arguments in deriving (2.51), we readily obtain that

$$a_{p_1,0} = a_{p_1-1,1} = a_{p_1-2,2} = a_{p_1-3,3}.$$

This together with (2.55) and (2.56) with $k_1 = 0$ implies

$$b_{p_1-3,0} = b_{p_1-4,1} = 0. (2.58)$$

Hence, it is deduced from (2.57) and (2.58) that $a_{p_1-4,4} = 0$, and combining (2.56) with $k_1 = 1$ yields that $b_{p_1-5,2} = 0$. Setting $k_2 = 1$ in (2.57), it is easy to verify that $a_{p_1-5,5} = 0$ due to $b_{p_1-4,1} = b_{p_1-5,2} = 0$. Repeating this procedure successively, we will get (2.43) and (2.54).

By induction, it holds that $a_{i,j} = b_{i,j} = 0$ for all $i, j \in \mathbb{N}_0$. The proof of Lemma 2.2 is thus complete in the second case. \Box

Remark 2.7. In the case of n = m, the proof of Lemma 2.2 should be slightly modified. The only difference is to replace (2.45) and (2.46) by

$$(f_m^{\pm})^3 \frac{a_{p-3m,3}}{(p-3m)!3!(m!)^3} + \frac{a_{p-2m,2}}{(p-2m)!2} \frac{(f_m^{\pm})^2}{(m!)^2} + \frac{a_{p-m,1}}{(p-m)!} \frac{f_m^m}{m!} + \frac{a_{p,0}}{p!} = 0 \qquad (2.59)$$

and

$$(f_m^{\pm})^2 \frac{3a_{p-3m,3}}{(p-3m)!3!(m!)^2} + \frac{2a_{p-2m,2}}{(p-2m)!2} \frac{(f_m^{\pm})}{(m!)} + \frac{a_{p-m,1}}{(p-m)!} = 0,$$
(2.60)

respectively. Similar to the derivation of (2.47), we can obtain $a_{p-3m,3} = a_{p-2m,2} = 0$. This together with (2.59) and (2.60) also gives that

$$a_{p-3m,3} = a_{p-2m,2} = a_{p-m,1} = a_{p,0} = 0.$$

Proceeding with the same lines as for the case n < m, we can also prove $w_1 = w_2 \equiv 0$ when n = m.

3. Characterization of radiating sources

This section is devoted to proving Theorems 1.2 and 1.3. One should note that the inverse source problem for recovering a source term is linear, whereas the inverse medium problems for shape identification and medium recovery are both nonlinear. Hence, the techniques for extracting source information from measurement data are usually easier than inverse medium scattering problems. Lemma 3.1 below can be regarded as the analogue of Lemma 2.2 for inverse source problems.

Lemma 3.1. Let $w \in H^1(B_1)$ be a solution to

$$\begin{cases} \Delta w + \kappa^2 \mathfrak{n}(x)w = s & in \quad B_1, \\ w = 0, \frac{\partial w}{\partial \nu} = 0 & on \quad \Gamma \cap B_1, \end{cases}$$
(3.1)

where $\mathfrak{n}(x)$ is analytic in B_1 and $O \in \Gamma$ is a weakly singular point. The source term s(x) is supposed to satisfy the elliptic equation

$$\Delta s(x) + A(x) \cdot \nabla s(x) + b(x)s(x) = 0 \text{ in } B_1, \qquad (3.2)$$

where $A(x) = (a_1(x), a_2(x))$ and b(x) are both analytic in B_1 . Then

$$w = s \equiv 0 \ in \ B_1. \tag{3.3}$$

Proof. Since w and s are real-analytic in B_1 , they can be expanded into the Taylor series

$$w(x) = \sum_{i,j\geq 0} \frac{w_{i,j}}{i!j!} x_1^i x_2^j, \quad s(x) = \sum_{i,j\geq 0} \frac{s_{i,j}}{i!j!} x_1^i x_2^j, \quad x = (x_1, x_2) \in B_1.$$
(3.4)

Taking Δ to the equation of w and using the governing equation of s, we find

$$\Delta\Delta w + \kappa^2 \Delta(\mathfrak{n}(x)w) = -A(x) \cdot \nabla s(x) - b(x)s(x).$$
(3.5)

From (3.1), it follows that, for any integer $l \ge 2$, the statement $w_{i,j} = 0$, $i + j \le l$ leads to $s_{i,j} = 0, i + j \le l - 2$. Further, similar to the derivation of (2.53), one can deduce from (3.5) and the relations $w_{i,j} = 0, i + j = l, j \le 3$; $w_{i,j} = 0, i + j \le l - 1$ and $s_{i,j} = 0, i + j \le l - 3$ that $w_{i,j} = 0, i + j = l, j \ge 4$. Hence, using the same method as employed in the proof of Lemma 2.2, one can prove (3.3). We omit the details for brevity. \Box

Remark 3.2. Lemma 3.1 applies to analytical source terms s(x) whose lowest order Taylor expansion at O is harmonic. By [19], the solutions to (3.2) process such a property.

Lemma 3.3. If the source term s is only required to be analytic in Lemma 3.1, then

$$s(O) = |\nabla s(O)| = 0.$$

Proof. The analyticity of \mathfrak{n} and s guarantees the same Taylor expansions as in (3.4). Employing the same arguments in steps 1-2 in the proof of Lemma 2.2 yields s(O) = 0. The method for proving (2.38) in the proof of Lemma 2.2 could directly lead to $|\nabla s(O)| = 0$. \Box

Now we are ready to prove Theorems 1.2 and 1.3, by applying Lemmata 3.3 and 3.1, respectively.

Proof of Theorem 1.2. (i) Assuming $v^{\infty} = 0$, then we obtain $v \equiv 0$ in |x| > R by Rellich's lemma and $v \equiv 0$ in $\mathbb{R}^2 \setminus \overline{D}$ by the unique continuation of the Helmholtz equation (see [17, Theorem 17.2.6, Chapter XVII]). In particular, the Cauchy data $v, \partial_{\nu}v$ vanish on $\Gamma_{\epsilon} = \partial D \cap B_{\epsilon}(O)$ for some $\epsilon > 0$. Since Γ_{ϵ} is piecewise analytic and the Cauchy data are both analytic on Γ_{ϵ} , by the Cauchy-Kovalevski theorem we can extend v from $D \cap B_{\epsilon}(O)$ to B_{ϵ} . Hence, the extended function v satisfies

$$\begin{cases}
\Delta v + \kappa^2 \mathfrak{n}(x)v = S & \text{in } B_{\epsilon}, \\
v = 0, \frac{\partial v}{\partial \nu} = 0 & \text{on } \Gamma_{\epsilon},
\end{cases}$$
(3.6)

where S is the analytical extension of s around O. Applying Lemma 3.3 gives $s(O) = |\nabla s(O)| = 0$, which contradicts the assumption that $|s(O)| + |\nabla s(O)| > 0$.

- (ii) Suppose that v can be analytically continued from $B_R \setminus \overline{D}$ to $B_{\epsilon}(O)$ for some $\epsilon > 0$. The extended solution obviously satisfies $\Delta v + \kappa^2 \mathfrak{n}(x)v = 0$ in $B_{\epsilon}(O)$. On the other hand, by Lemma 2.1 we can extend v from $D \cap B_{\epsilon}(O)$ to B_{ϵ} as the solution of $\Delta w + \kappa^2 \mathfrak{n}(x)w = S$ in $B_{\epsilon}(O)$. Now, we can observe that the difference w v satisfies the same Cauchy problem as in (3.6). Applying Lemma 3.3 yields the same contradiction to $|s(O)| + |\nabla s(O)| > 0$. \Box
- **Proof of Theorem 1.3.** (i) Suppose that there are two sources s and \tilde{s} which generate identical far-field patterns and have the same support \overline{D} . Denote by v and \tilde{v} the wave fields radiated by s and \tilde{s} , respectively. By Rellich's lemma and the unique continuation, we know $v = \tilde{v}$ in $\mathbb{R}^2 \setminus \overline{D}$. Setting $u := v \tilde{v}$, it follows that

$$\begin{cases} \Delta u + \kappa^2 \mathfrak{n}(x)u = s - \tilde{s} & \text{in } B_{\epsilon}, \\ u = 0, \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial D \cap B_{\epsilon}, \end{cases}$$
(3.7)

for some $\epsilon > 0$. Applying Lemma 3.3 gives $s(O) = \tilde{s}(O)$ and $\nabla s(O) = \nabla \tilde{s}(O)$.

(ii) Applying Lemma 3.1 to (3.7), we get $s = \tilde{s}$ near O, because the difference $s - \tilde{s}$ on the right hand side also satisfies the elliptic equation (1.4). Applying the unique continuation for elliptic equation (see [17, Theorem 17.2.6, Chapter XVII]) gives $s \equiv \tilde{s}$ on D. \Box

4. Appendix: Proof of Lemma 2.6

Let $m \geq 2$ be the order of the weakly singular point $O \in \Gamma$ and let $k \in \mathbb{N}$ be the integer specified in Lemma 2.6 where $2 \leq n < m$ is the integer satisfying (2.15). Recall that $g := w|_{\Gamma}$ and $h := \partial_2 w|_{\Gamma}$ are given by (2.12) and (2.11), respectively. It follows from (2.7) and (2.8) that $g_j^{\pm} = h_j^{\pm} = 0$ for all $j \in \mathbb{N}_0$. Before proving Lemma 2.6, we need to introduce several new index sets and prepare some lemmas.

Definition 4.1. For $(i, j) \in \Upsilon^a_{\alpha}$, we denote the set of all pair sequences $\{(i_k, j_k)\}_{k=1}^d$ satisfying (2.22) by $\Lambda^a_{i,j,\alpha}$. Here, Υ^a_{α} is given by Definition 2.5. Furthermore, we define the set $\Lambda^a_{i,j,\alpha,m} := \{\{(i_k, j_k)\}_{k=1}^d \in \Lambda^a_{i,j,\alpha} : i_k < m\}$ and denote by

$$\mathcal{M}_{\alpha}^{a} := \sum_{(i,j)\in\Upsilon_{\alpha}^{a}} \frac{C_{j}^{\alpha}a_{i,j}}{i!j!} \sum_{\{(i_{k},j_{k})\}_{k=1}^{d}\in\Lambda_{i,j,\alpha,m}^{a}} \sum_{k=1}^{d} \left(\frac{f_{i_{k}}}{i_{k}!}\right)^{j_{k}} C_{j-\alpha-\sum_{l< k}j_{l}}^{j_{k}}.$$
 (4.1)

Here, $C_b^a := b!/(a!(b-a)!)$ denotes the combination number with $0 \le a \le b$.

Remark 4.2. From the definition of \mathcal{M}^a_{α} , it is easily seen that

$$\mathcal{M}^{a}_{\alpha}x_{1}^{a} = \sum_{(i,j)\in\Upsilon^{a}_{\alpha}} \frac{C^{\alpha}_{j}a_{i,j}}{i!j!}x_{1}^{i}\sum_{\{(i_{k},j_{k})\}_{k=1}^{d}\in\Lambda^{a}_{i,j,\alpha,m}} \sum_{k=1}^{d} \left(\frac{f_{i_{k}}}{i_{k}!}x_{1}^{i_{k}}\right)^{j_{k}}C^{j_{k}}_{j-\alpha-\sum_{l\leq k}j_{l}}$$

Note that by definition we have $i + i_k j_k = a$ for $(i, j) \in \Upsilon^a_{\alpha}$ and $\{(i_k, j_k)\}_{k=1}^d \in \Lambda^a_{i,j,\alpha,m}$.

Now we make use of $\mathcal{M}^a_{\alpha} \in \mathbb{C}$ to express g^l_{\pm} and h^l_{\pm} for some l.

Lemma 4.3. Let the assumptions in Lemma 2.6 hold true.

(a) For $-(m+k) \leq l < m$, we have

$$\frac{g_{m+l+k}^{\pm}}{(m+l+k)!} = \sum_{\lambda \in J} 2\mathcal{M}_2^{\lambda+k} \frac{f_{l+m-\lambda}^{\pm}}{(l+m-\lambda)!} + \mathcal{M}_1^{l+m+k}.$$
(4.2)

Here, $J := \{\lambda \in \mathbb{Z} : -k \leq \lambda \leq l\}$. If $J = \emptyset$, then we denote $\sum_{\lambda \in J} = 0$. For l = m, we have

$$\frac{g_{2m+k}^{\pm}}{(2m+k)!} = \sum_{m < l \le 2m+k} \frac{f_l^{\pm}}{l!} 2\mathcal{M}_2^{2m-l+k} + \frac{3a_{k,3}}{k!3!} \frac{(f_m^{\pm})^2}{(m!)^2} + \frac{f_m^{\pm}}{m!} 2\mathcal{M}_2^{m+k} + \mathcal{M}_1^{2m+k}.$$
(4.3)

(b) It holds that

$$\frac{h_{3m+k}^{\pm}}{(3m+k)!} = \sum_{m < l \le 3m+k} \frac{f_l^{\pm} g_{3m-l+k}^{\pm}}{l!(3m-l+k)!} - \sum_{m < l \le \frac{3m+k}{2}} \left(\frac{f_l^{\pm}}{l!}\right)^2 \mathcal{M}_2^{3m-2l+k} + \frac{(f_m^{\pm})^3}{(m!)^3} \frac{a_{k,3}}{k!3!}$$

L. Li et al. / Journal of Functional Analysis 284 (2023) 109800

$$+\frac{(f_m^{\pm})^2}{(m!)^2}\mathcal{M}_2^{m+k} + \frac{f_m^{\pm}}{m!}\mathcal{M}_1^{2m+k} + \mathcal{M}_0^{3m+k}.$$
(4.4)

Proof. (a) Denote by $A^{\pm} := \{f_j^{\pm} : j \ge m\}$, and recall (see e.g., (2.12))

$$g(x_1) = \sum_{i \ge 0, j \ge 1} \frac{j a_{i,j}}{i! j!} x_1^i \left(\sum_{l=n}^{m-1} \frac{f_l}{l!} x_1^l + \sum_{l=m}^{\infty} \frac{f_l^{\pm}}{l!} x_1^l \right)^{j-1} = \sum_{l \in \mathbb{N}_0} \frac{g_{\pm}^l}{l!} x_1^l \quad \text{for} \quad x_1 \le 0.$$

Then, by comparing the coefficients of x_1^{l+m+k} in the expansion of g, it follows that when $-(m+k) \le l < m$,

$$\begin{split} & \frac{g_{m+l+k}^{\pm}}{(m+l+k)!} x_1^{m+l+k} \\ &= \sum_{(i,j)\in\Upsilon_1^{m+l+k}} \left[\frac{ja_{i,j}}{i!j!} x_1^i \sum_{\{(i_k,j_k)\}_{k=1}^d \in \Lambda_{i,j,1,m}^{m+l+k}} \sum_{k=1}^d \left(\frac{f_{i_k}}{i_k!} x_1^{i_k} \right)^{j_k} C_{j-1-\sum_{l < k} j_l}^{j_k} \right] \\ &+ \sum_{\lambda \in J} \left[\sum_{(i,j)\in\Upsilon_2^{\lambda+k}} \frac{ja_{i,j}}{i!j!} x_1^i \frac{f_{l+m-\lambda}^{\pm}(j-1)}{(l+m-\lambda)!} x_1^{l+m-\lambda} \sum_{\{(i_k,j_k)\}_{k=1}^d \in \Lambda_{i,j,2,m}^{\lambda+k}} \right. \\ & \times \sum_{k=1}^d \left(\frac{f_{i_k}}{i_k!} x_1^{i_k} \right)^{j_k} C_{j-2-\sum_{l < k} j_l}^{j_k} \right] \\ &+ \eta_l^{\pm} x_1^{m+l+k}. \end{split}$$

Here, η_l^{\pm} are the sum of a finite number of products relying on at least two elements from the set A^{\pm} and $a_{i,j}$ with $(i,j) \in J_{k,l} := \{(i,j) : i \leq l+m+k-(2m+(j-3)n), j \geq 3\}$. This together with the Remark 4.2 yields that

$$\frac{g_{m+l+k}^{\pm}}{(m+l+k)!}x_1^{m+l+k} = \left(\mathcal{M}_1^{l+m+k} + \sum_{\lambda \in J} \frac{2\mathcal{M}_2^{\lambda+k} f_{l+m-\lambda}^{\pm}}{(l+m-\lambda)!} + \eta_l^{\pm}\right)x_1^{m+l+k}, \quad x_1 \le 0.$$

Further, when l < m, it is easy to verify that i + jn < k + 3n for $(i, j) \in J_{k,l}$. Then, in view of the induction hypothesis on $a_{i,j}$ in Lemma 2.6 (see formula (2.23)), it can be deduced that $a_{i,j} = 0$ for $(i, j) \in J_{k,l}$, implying $\eta_l^{\pm} = 0$. This thus proves the equality (4.2).

Similarly, to prove (4.3) we compare the coefficients of x_1^{2m+k} in the expansion of g and use Remark 4.2 to deduce that

$$\frac{g_{2m+k}^{\pm}}{(2m+k)!} = \sum_{m < l \le 2m+k} \frac{f_l^{\pm}}{l!} 2\mathcal{M}_2^{2m-l+k} + \frac{3a_{k,3}}{k!3!} \frac{(f_m^{\pm})^2}{(m!)^2} + \frac{f_m^{\pm}}{m!} 2\mathcal{M}_2^{m+k} + \mathcal{M}_1^{2m+k} + \zeta^{\pm}.$$

Here, ζ^{\pm} are the sum of a finite number of products relying on at least two elements from the set A^{\pm} and $a_{i,j}$ with $(i,j) \in J_{k,m} := \{(i,3) : i \leq 2m + k - (2m + 1)\} \cup \{(i,j) : i \leq 2m + k - (2m + (j - 3)n), j \geq 4\}$. Further, note that $n \geq 2$, it is easy to verify that i + 3n < k + 3n with j = 3 and $i + j \leq k - n + 3 < k + 2$ with $j \geq 4$ when $(i,j) \in J_{k,m}$. Thus, we deduce from the assumptions on $a_{i,j}$ that $a_{i,j} = 0$ for $(i,j) \in J_{k,m}$, implying that $\zeta^{\pm} = 0$. This implies that (4.3) holds.

(b) We first recall the expansion of h by

$$h(x_1) = \sum_{i \ge 0, j \ge 0} \frac{a_{i,j}}{i! j!} x_1^i \left(\sum_{l=n}^{m-1} \frac{f_l}{j!} x_1^l + \sum_{l=m}^{\infty} \frac{f_l^{\pm}}{j!} x_1^l \right)^j = \sum_{l \in \mathbb{N}_0} \frac{h_{\pm}^l}{l!} x_1^l \qquad x_1 \le 0.$$

Equating the coefficients of x_1^{3m+k} in the above expansion and using Remark 4.2, we get

$$\frac{h_{3m+k}^{\pm}}{(3m+k)!} = \sum_{m < l \le 3m+k} \frac{f_l^{\pm}}{l!} \left(\sum_{\lambda \in J_1} \frac{2\mathcal{M}_2^{\lambda+k} f_{3m-l-\lambda}^{\pm}}{(3m-l-\lambda)!} + \mathcal{M}_1^{3m-l+k} \right) + \sum_{m < l \le \frac{3m+k}{2}} \left(\frac{f_l^{\pm}}{l!} \right)^2 \mathcal{M}_2^{3m-2l+k} + \frac{(f_m^{\pm})^3}{(m!)^3} \frac{a_{k,3}}{k!3!} + \frac{(f_m^{\pm})^2}{(m!)^2} \mathcal{M}_2^{m+k} + \frac{f_m^{\pm}}{m!} \mathcal{M}_1^{2m+k} + \mathcal{M}_0^{3m+k} + \gamma^{\pm}$$
(4.5)

where $J_1 := \{\lambda \in \mathbb{Z} : -k \leq \lambda \leq 2m - l, \lambda \neq 3m - 2l\}; \gamma^{\pm}$ are the sum of a finite number of products relying on at least three elements from the set A^{\pm} and $a_{i,j}$ with $(i, j) \in J_{k,m}$, where $J_{k,m}$ is given by the assertion (a). Employing similar arguments as for ζ^{\pm} in the assertion (a), it follows from the induction hypothesis on $a_{i,j}$ that $\gamma^{\pm} = 0$. On the other hand, it is easily seen that 3m - l < 2m when l > m. Thus, from (4.2), we have

$$\frac{g_{3m-l+k}^{\pm}}{(3m-l+k)!} = \sum_{-k \le \lambda \le 2m-l} \frac{2\mathcal{M}_2^{\lambda+k} f_{3m-l-\lambda}^{\pm}}{(3m-l-\lambda)!} + \mathcal{M}_1^{3m-l+k}$$

This together with (4.5) and the fact that $\gamma^{\pm} = \gamma_m^{\pm} = 0$ proves the relation (4.4). \Box

To proceed we introduce two new sets of indices.

Definition 4.4. Given $j \in \mathbb{N}, j < m$, the set \mathbb{F}_j is defined by

$$F_j = \{a: \exists b > m, j + m = a + b, a \ge n, f_b^+ \ne f_b^-\}$$

and the subset $F_{j,1}$ of F_j is defined by

$$F_{j,1} = \{a \in F_j : \exists a_1 \ge n, b_1 > m, a + m = a_1 + b_1, f_{b_1}^+ \neq f_{b_1}^- \}.$$

Lemma 4.5. Under the assumptions of Lemma 2.6, the relation $g(x_1) \equiv 0$ for all $x_1 \in (-1/2, 1/2)$ (see (2.12) for the definition of g) implies that

$$\mathcal{M}_2^{l+k} = 0 \quad \text{for all} \quad -k \le l < m. \tag{4.6}$$

Proof. Assume $-k \leq l < n$. From the definition of the index sets Υ^a_{α} (see Definition 2.5), it follows for $(i, j) \in \Upsilon^{l+k}_2$ that,

$$i = l + k, \qquad \text{if } j = 2,$$

$$i \le l + k - (j - 2)n, \qquad \text{if } j \ge 3.$$

This leads to

$$i+jn \leq l+2n+k < 3n+k \quad \text{ if } \quad (i,j) \in \Upsilon_2^{l+k},$$

which together with the induction hypothesis of Lemma 2.6 yields $a_{i,j} = 0$ when $(i, j) \in \Upsilon_2^{l+k}$. By Definition 4.1, this implies

$$\mathcal{M}_2^{l+k} = 0 \quad \text{for } -k \le l < n. \tag{4.7}$$

Below we only need to consider the case of $l \ge n$. In the sequel, we set $f_p = f_p^+ = f_p^-$ if $f_p^+ = f_p^-$ for some p > m.

We first assume that F_l is empty. Combining (4.2) in Lemma 4.3, the relations in (4.7) and $g_{m+l+k}^{\pm} = 0$, we arrive at

$$2\mathcal{M}_{2}^{l+k}\frac{f_{m}^{+}}{m!} + \sum_{n \leq \lambda < l} \frac{2\mathcal{M}_{2}^{\lambda+k}f_{l+m-\lambda}}{(l+m-\lambda)!} + \mathcal{M}_{1}^{l+m+k}$$
$$= 2\mathcal{M}_{2}^{l+k}\frac{f_{m}^{-}}{m!} + \sum_{n \leq \lambda < l} \frac{2\mathcal{M}_{2}^{\lambda+k}f_{l+m-\lambda}}{(l+m-\lambda)!} + \mathcal{M}_{1}^{l+m+k},$$

implying that

$$\mathcal{M}_{2}^{l+k}\left(\frac{f_{m}^{+}}{m!} - \frac{f_{m}^{-}}{m!}\right) = 0.$$
(4.8)

This together with the fact that $f_m^+ \neq f_m^-$ proves (4.6).

Now, suppose that $F_l \neq \emptyset$. Again using (4.2), (4.7) and $g_{m+l+k}^{\pm} = 0$ we deduce that

$$\sum_{\lambda_0 \in \mathcal{F}_l} \frac{2f_{m+l-\lambda_0}^{\pm}}{(m+l-\lambda_0)!} \mathcal{M}_2^{\lambda_0+k} + \frac{2f_m^{\pm}}{m!} \mathcal{M}_2^{l+k}$$
$$= \mathcal{M}_1^{m+l+k} - \sum_{n \le \lambda_0 < l, \lambda_0 \notin \mathcal{F}_l} \frac{2\mathcal{M}_2^{\lambda_0+k} f_{l+m-\lambda_0}}{(l+m-\lambda_0)!}.$$
(4.9)

Split the set F_l into two classes $F_{l,1}$ and $F_l \setminus F_{l,1}$. For $\lambda_0 \in F_l \setminus F_{l,1}$, similar to the derivation of (4.8), it follows from (4.2), (4.7) and $g_{\lambda_0+m+k}^{\pm} = 0$ that

$$\mathcal{M}_2^{\lambda_0+k}\left(\frac{f_m^+}{m!}-\frac{f_m^-}{m!}\right)=0,$$

leading to

$$\mathcal{M}_2^{\lambda_0 + k} = 0. \tag{4.10}$$

For any $\lambda_0 \in F_{l,1}$, one can deduce from (4.2), (4.7) and $g_{\lambda_0+m+k}^{\pm} = 0$ that

$$\sum_{\lambda_1 \in \mathcal{F}_{\lambda_0}} \frac{2f_{\lambda_0+m-\lambda_1}^{\pm}}{(\lambda_0+m-\lambda_1)!} \mathcal{M}_2^{\lambda_1+k} + \frac{2\mathcal{M}_2^{\lambda_0+k}f_m^{\pm}}{m!}$$
$$= \mathcal{M}_1^{\lambda_0+m+k} - \sum_{n \le \lambda_0 < \lambda_1, \lambda_1 \notin \mathcal{F}_{\lambda_0}} \frac{2\mathcal{M}_2^{\lambda_1+k}f_{\lambda_0+m-\lambda_1}}{(\lambda_0+m-\lambda_1)!}$$

Repeating this process we can divide the set F_{λ_0} into $F_{\lambda_0,1}$ and $F_{\lambda_0} \setminus F_{\lambda_0,1}$ to generate a new set F_{λ_1} . Then we split F_{λ_1} into $F_{\lambda_1,1}$ and $F_{\lambda_1} \setminus F_{\lambda_1,1}$ to continue this process. After a finite number of steps we may end up this process with the empty set $F_{\lambda_r} = \emptyset$ for some $\lambda_r \geq n$. In this way we can get the sequence $\lambda_0 > \lambda_1 > \cdots \geq \lambda_r$. For simplicity, we assume that there is only one chain $\lambda_0 \to \lambda_1 \to \cdots \to \lambda_r$ and that F_{λ_r} is the first empty set. The case of multiple chains can be proved similarly. Further, with the aid of (4.2), (4.7) and $g_{\lambda_l+m+k}^{\pm} = 0$ with $0 \leq l \leq r$, we have for each $l, 0 \leq l \leq r - 1$ that

$$\sum_{\lambda_{l+1}\in F_{\lambda_l}} \frac{2\mathcal{M}_2^{\lambda_{l+1}+k} f_{\lambda_l+m-\lambda_{l+1}}^{\pm}}{(\lambda_l+m-\lambda_{l+1})!} + \frac{2f_m^{\pm}}{m!} \mathcal{M}_2^{\lambda_l+k}$$
$$= \mathcal{M}_1^{\lambda_l+m+k} - \sum_{n \le \lambda_0 < \lambda_l, \lambda_{l+1} \notin F_{\lambda_l}} \frac{2\mathcal{M}_2^{\lambda_{l+1}+k} f_{\lambda_l+m-\lambda_{l+1}}}{(\lambda_l+m-\lambda_{l+1})!}$$
(4.11)

and

$$2\mathcal{M}_2^{\lambda_r+k}\frac{f_m^{\pm}}{m!} = -\sum_{n\leq\lambda<\lambda_r}\frac{2\mathcal{M}_2^{\lambda+k}f_{\lambda_r+m-\lambda}}{(\lambda_r+m-\lambda)!} - \mathcal{M}_1^{\lambda_r+m+k}$$

The last identity together with the fact that $f_m^+ \neq f_m^-$ implies $\mathcal{M}_2^{\lambda_r+k} = 0$. This combined with (4.11) for l = r - 1 gives the relation

$$\mathcal{M}_2^{\lambda_{l-1}+k} = 0.$$

Repeating the same arguments, we can obtain (4.10). Combining with (4.9) and (4.10) gives (4.6). The proof is thus completed. \Box

Now we are in a position to finish the proof of Lemma 2.6.

Proof of Lemma 2.6. Let

m

$$D_{k,l} = \mathcal{M}_{3-l}^{lm+k}$$
 for $l = 1, 2, 3$.

From the formula (4.1) in Definition 4.1, it is deduced that $D_{k,l} \in \mathbb{C}$ depends on $a_{i,j}$ with $(i,j) \in \Upsilon_{3-l}^{lm+k}$ and only on the coefficients f_l of $f(x_1)$ with l < m.

We first prove (2.24). Using (4.3) in Lemma 4.3 and $g_{2m+k}^{\pm} = 0$, we get

$$\sum_{\substack{(4.12)$$

Note that 2m-l < m when m < l < 2m. The relation (2.24) then follows from Lemma 4.5 and (4.12).

Now we need to prove (2.25). Recalling (4.4) in Lemma 4.3 and $h_{3m+k}^{\pm} = 0$, we have

$$0 = \sum_{m < l \le 3m+k} \frac{f_l^{\pm} g_{3m-l+k}^{\pm}}{l!(3m-l+k)!} - \sum_{m < l \le \frac{3m+k}{2}} \left(\frac{f_l^{\pm}}{l!}\right)^2 \mathcal{M}_2^{3m-2l+k} + \frac{(f_m^{\pm})^3}{(m!)^3} \frac{a_{k,3}}{k!3!} + \frac{(f_m^{\pm})^2}{(m!)^2} D_{k,1} + \frac{f_m^{\pm}}{m!} D_{k,2} + D_{k,3}.$$

Note that g_{3m-l+k}^{\pm} denotes the (3m-l+k)th coefficient of $g(x_1)$ defined by (2.12). Further, it is easily seen that 3m-2l < m when l > m. Thus, using the results of Lemma 4.5 together with $g_{3m-l+k}^{\pm} = 0$, it follows that (2.25) holds. The proof is thus complete. \Box

Data availability

No data was used for the research described in the article.

Acknowledgments

The work of L. Li and J. Yang are partially supported by the National Science Foundation of China (11961141007,61520106004) and Microsoft Research of Asia. The work of G. Hu is supported by the National Natural Science Foundation of China (No. 12071236) and the Fundamental Research Funds for Central Universities in China (No. 63213025).

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